



## Linear axis for collaborative robots LIFTKIT





### Heritage of innovation for technology leadership

Ewellix is a global innovator and manufacturer of linear motion and actuation solutions. Today, our state-of-the-art linear solutions are designed to increase machine performance, maximise uptime, reduce maintenance, improve safety and save energy.

### Technology leadership

Our journey began **over 50 years** ago as part of the SKF Group, and our history with SKF provided us with the **expertise to continuously develop new technologies** and use them to create cutting edge products that offer our customers a competitive advantage.

In 2019, we became independent from SKF and changed our name to Ewellix. **We are proud of our heritage.** This gives us a unique foundation on which to build an agile business with engineering excellence and innovation as our core strengths.

### Global presence and local support

With our **global presence**, we are uniquely positioned to deliver **standard components and custom-engineered solutions**, with full technical and applications support around the world. The long lasting relationships with our distributor partners allow us to support customers in a variety of different industries. At Ewellix, we don't just provide products; **we engineer integrated solutions** that help customers realise their ambitions.



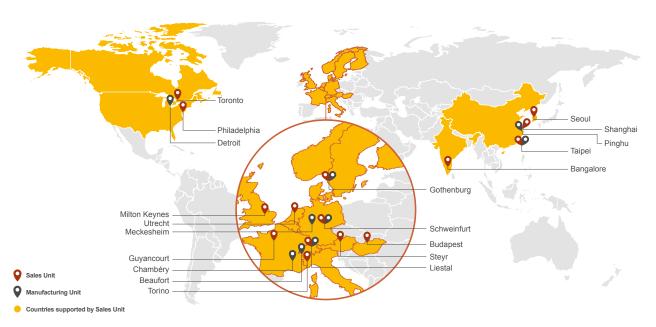
1400 employees



16 sales units



9 factories





### Benefits for handling

Fully automated pick and place solutions are becoming a new standard with packaging stations.



The main challenge for packaging system manufacturers is to design multi-axis systems in a simple and cost efective way.

A typical application that benefts from an added linear axis is palletizing of boxes. Stacking on pallets can start at foor level, but the stack can be up to 2 m high. A standard collaborative robot does not have such a large vertical working range.

Ewellix provides efective solutions to complete vertical adjustment in a smart way, providing a ready to mount additional linear axis to the robot. While stacking a pallet, the base of the robot can be lifted or lowered to work at a more optimal position.



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### Operating range extension

- Vertical lifting of the cobot by up to 900 mm (1.400 mm on request) with compact retracted height
- Robust pillar design for industrial use, vibration free motion and virtually maintenance free

### Plug-and-play solution

- Hardware interface compatible with UR3, UR5, UR10 and UR16 robots
- · Universal Robots+ certified product
- Software control integrated with UR controller (URCaps) for easy motion programming
- Basic control option with digital I/O for all cobot manufacturers

### Cost savings and higher productivity

Cobots combined with Ewellix LIFTKIT provide a cost-effective solution to upgrade an existing assembly shop, moving from a manual handled to a fully automatized line.





### **Technical data**

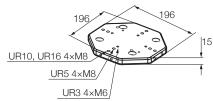
	Unit	LIFTKIT-UR-601	LIFTKIT-00-601
Pillar type	-	TLT	TLT
Mechanical			
	N.	1.500	1.500
Push load	N	1 500	1 500
Pull load	N	0	0
Speed	mm/s	80	80
Stroke	mm	500 – 900	500 – 900
Retracted length (software controlled)	mm	Stroke/2 + 275	Stroke/2 + 275
Height of attachment plates	mm	2x15	1x15
Cross section	mm	163x163	163x163
Type of protection	ΙP	40	40
Ambient temperature	°C	+10 to +40	+10 to +40
Robots compatibility	-	UR3, UR5, UR10, UR16, e-Series	Any robot
Cable management	-	Threads on pillar and interface	Threads on pillar to attach
		plate to attach cable management	cable management
Electrical			
	V/A	120 AC / 6.5 A	120 AC / 6.5 A
Voltage/Current	V/A		
		230 AC / 3,3 A	230 AC / 3,3 A
		24 DC / 10 A	24 DC / 10 A
Emergency stop	-	Connection to UR safety I/O	Connection to robot safety I/O
Communication			
Control interface	-	URCaps plugin compatible with CB3.1 / Polyscope 3.6 or higher	Digital I/O control, RS232 interface for external software control (no software provided)
Positioning, repeatability	mm	±1	±1 ,
Accessible positions	-	any	2 memory positions programmable
Feedback	-	Position feedback via URCaps	Position feedback for memory positions via output signal
Soft start and stop	-	Implemented for smooth operation	,, ,
Software control	-	URcap	RS232 interface for external software control (no control software provided)

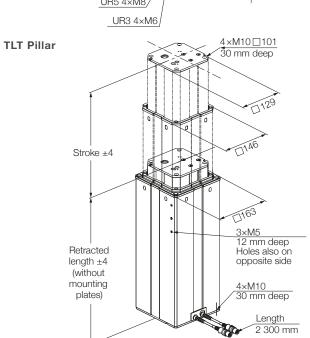


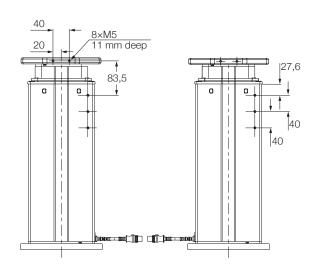
### **Dimensional drawing**

### **TLT telescopic pillar**

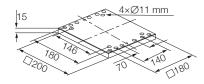
### Robot attachment plate



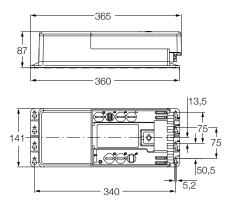




### Bottom fixation plate



### **Control unit**

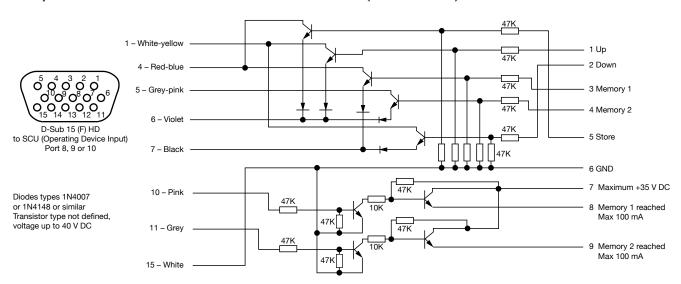


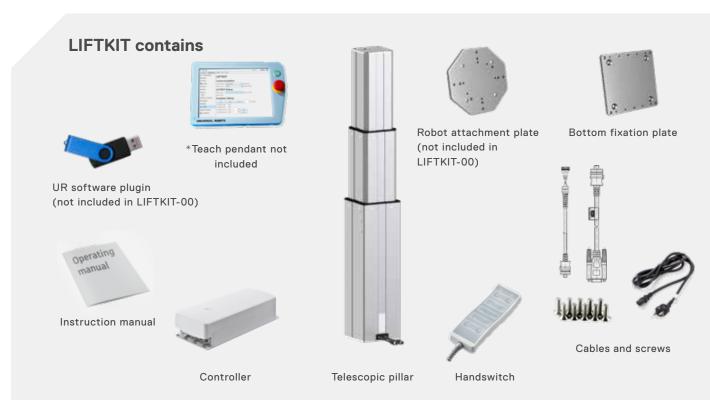


# Cable management Threads for cable management attachments

# Electrical 230/120 V AC 24 V DC Controller + Power supply

### Example of LIFTKIT-00 interface board to robot PLC (not included)







### Software functionality

The URCaps software for the LIFTKIT allows easy positioning access directly within the UR Polyscope environment.

### Setup

In the installation tab, the user can manually move the linear axis in both directions and define multiple user specific positions, that are accessible in programming mode.

### **Motion programming**

Within the UR motion program, the LIFTKIT axis is easily integrated through a URCaps command module. Simply insert this element from the structure tab at the desired position of the program. Additionally, reading and setting positions is possible through a script function.

### Safety elements

The LIFTKIT has a range of safety elements built in to allow its integration into a robot application.

### Software updates

To download the latest software update please check on ewellix.com/support/library/software updates.

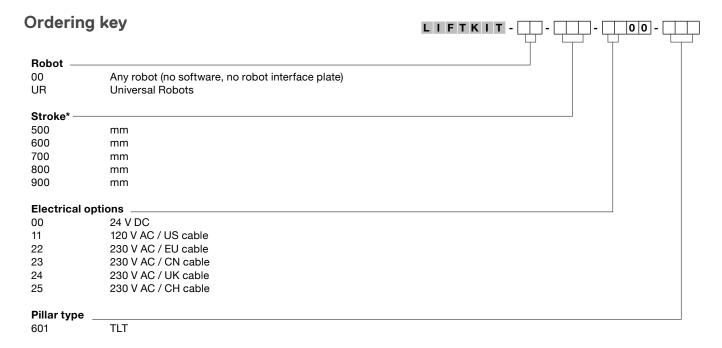
### NOTE:

The LIFTKIT is not a functional safety system compliant with EN ISO 13489-1 or IEC 62061. To integrate the LIFTKIT into a functional safety chain, external safety devices have to be integrated into the overall system.





LIFTKIT software functionality



<sup>\*</sup> longer stroke up to 1 400 mm available on request



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